

Package ‘explodemap’

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Title Hierarchical Exploded-View Cartography

Version 0.2.0

Description Tools for generating hierarchical exploded-view maps from dense administrative boundary data. The package applies rigid-body translations to polygon geometries using a centroid-driven vector field, preserving the internal geometry of each feature while separating units within and across regions. Parameters can be derived analytically from dataset geometry using closed-form models for regional separation and local expansion. The package also includes grouped layouts, optional bounded collision refinement, and an interactive focus-map widget for selected-area inspection in 'htmlwidgets' and 'Shiny'. It implements the methodology described in George Arthur (2026) <<https://github.com/PrigasG/explodemap>> ``A Hierarchical Vector-Based Framework for Multi-Scale Exploded-View Cartography".

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URL <https://prigasg.github.io/explodemap/>,
<https://github.com/PrigasG/explodemap>

BugReports <https://github.com/PrigasG/explodemap/issues>

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cache_clear	<i>Clear explodemap download cache</i>
-------------	--

Description

Clear explodemap download cache

Usage

```
cache_clear(key = NULL)
```

Arguments

key	Specific cache key to clear, or NULL to clear all
-----	---

Value

Invisibly returns NULL. The function is called for its side effect of deleting cached .rds files and reporting what was removed.

cache_list	<i>List cached datasets</i>
------------	-----------------------------

Description

List cached datasets

Usage

```
cache_list()
```

Value

Invisibly returns a character vector of cached .rds file names. The visible output is a message listing the cache directory and file sizes, or a message that the cache is empty.

calibration_row	<i>Extract calibration row from an exploded_map</i>
-----------------	---

Description

Returns a one-row data.frame suitable for binding across datasets to build a calibration table.

Usage

```
calibration_row(x)
```

Arguments

x An exploded_map object

Value

A one-row data.frame

compute_stats	<i>Compute geometry statistics for parameter derivation</i>
---------------	---

Description

Extracts w_{bar} , R_{local} , n_{bar} , n_{regions} , and the tightness ratio from a projected sf object with a grouping column.

Usage

```
compute_stats(
  sf_obj,
  region_col,
  centroid_fun = c("centroid", "point_on_surface")
)
```

Arguments

sf_obj	Projected sf object
region_col	Name of the grouping column
centroid_fun	"centroid" (default) or "point_on_surface"

Value

A named list of geometry statistics

derive_params	<i>Derive displacement parameters from geometry statistics</i>
---------------	--

Description

Implements Analytical Results 1 and 2 from the paper: $\alpha_r = \gamma_r * w_{\text{bar}} / (2 * \sin(\pi / n_{\text{regions}}))$ $\alpha_l = \gamma_l * 2 * R_{\text{local}} / \sqrt{n_{\text{bar}}}$

Usage

```
derive_params(stats, gamma_r = 3, gamma_l = 1.136, p = 1.25)
```

Arguments

stats	Output of <code>compute_stats()</code>
gamma_r	Regional clearance coefficient (default 3.0)
gamma_l	Local clearance coefficient (default 1.136)
p	Distance scaling exponent (default 1.25)

Value

Named list with alpha_r, alpha_l, p, gamma_r, gamma_l

estimate_block_radii *Estimate block radius for each region*

Description

Computes the 85th percentile of distances from child-unit centroids to their region centroid. The 85th percentile is preferred over the maximum because the maximum is sensitive to outlier units and produces over-conservative block radii.

Usage

```
estimate_block_radii(
  sf_obj,
  region_col,
  quantile_p = 0.85,
  centroid_fun = c("centroid", "point_on_surface")
)
```

Arguments

sf_obj	Projected sf object with region column
region_col	Grouping column name
quantile_p	Quantile for radius estimation (default 0.85)
centroid_fun	"centroid" or "point_on_surface"

Value

data.frame with columns: region, block_radius, cx, cy, n_units

explode_grouped *Create a three-level grouped exploded map*

Description

Combines Level 1 (local explosion within regions) with Level 2/3 (anchor-based region block placement). This is the full three-level extension from Section 12 of the paper.

Usage

```
explode_grouped(
  sf_obj,
  region_col,
  mode = c("auto", "auto_collision", "manual"),
  anchors = NULL,
  alpha_l = NULL,
  p = 1.25,
  gamma_l = 1.136,
  kappa = 1.8,
  padding = 50000,
  delta = 15000,
  lambda = 0.18,
  eta = 0.18,
  padding_sep = 20000,
  anchor_expand = NULL,
  anchor_buffer = NULL,
  density_scale = NULL,
  block_sep = NULL,
  max_iter = 60,
  fix_invalid = TRUE,
  centroid_fun = c("centroid", "point_on_surface"),
  plot = TRUE,
  export = NULL,
  label = "Grouped Layout",
  quiet = FALSE
)
```

Arguments

<code>sf_obj</code>	Projected sf object with region column
<code>region_col</code>	Grouping column name
<code>mode</code>	"auto", "auto_collision", or "manual"
<code>anchors</code>	For mode = "manual": data.frame with anchor positions
<code>alpha_l</code>	Local expansion parameter for Level 1 (metres)
<code>p</code>	Distance scaling exponent (default 1.25)
<code>gamma_l</code>	Local clearance coefficient (default 1.136); used if alpha_l is NULL
<code>kappa</code>	Radial expansion factor (default 1.8)
<code>padding</code>	Base padding (default 50000)
<code>delta</code>	Log-density scaling (default 15000)
<code>lambda</code>	Spring coefficient (default 0.18)
<code>eta</code>	Repulsion step (default 0.18)
<code>padding_sep</code>	Minimum block separation (default 20000)

anchor_expand, anchor_buffer, density_scale, block_sep	Optional aliases for kappa, padding, delta, and padding_sep, respectively. These names are convenient in Shiny dashboards where the controls describe the visual effect rather than the solver term.
max_iter	Max collision iterations (default 60)
fix_invalid	Auto-repair invalid geometries (default TRUE)
centroid_fun	"centroid" or "point_on_surface"
plot	Print plots (default TRUE). Automatically suppressed inside a live Shiny session; use <code>plot.grouped_exploded_map()</code> inside <code>renderPlot()</code> .
export	NULL, TRUE, or file path
label	Title for plots
quiet	If TRUE, suppress <code>message()</code> output. Default FALSE.

Details

The guarantees of Propositions 1-3 apply strictly at Level 1. Higher levels preserve structural grouping and directional correspondence rather than topological coverage.

Value

A `grouped_exploded_map` S3 object (inherits from `exploded_map`)

<code>explode_section</code>	<i>Explode one selected section and keep the rest as context</i>
------------------------------	--

Description

`explode_section()` is a dashboard-oriented helper for exploratory maps. It applies an exploded layout only to the requested section, then recombines the untouched remainder of the layer as geographic context. The result can be passed directly to `focus_map()` with `context_col` to fade or hide the non-selected features.

Usage

```
explode_section(
  sf_obj,
  section_col,
  section,
  region_col = section_col,
  layout = c("explode", "grouped"),
  context = c("fade", "hide", "none"),
  role_col = ".explodemap_role",
  all_values = "all",
  ...
)
```

Arguments

<code>sf_obj</code>	Projected sf object.
<code>section_col</code>	Column containing the high-level sections users choose from, such as "North", "Central", and "South".
<code>section</code>	Selected section value. Values in <code>all_values</code> explode the full layer.
<code>region_col</code>	Column used for the explosion inside the selected section. Defaults to <code>section_col</code> . For municipality drill-downs, this is often a county column.
<code>layout</code>	"explode" for <code>explode_sf()</code> or "grouped" for <code>explode_grouped()</code> .
<code>context</code>	"fade" or "hide" keeps non-selected features in the returned object as context; "none" drops them.
<code>role_col</code>	Name of the role column added to the output. Focus features are marked "focus" and context features are marked "context".
<code>all_values</code>	Values that mean "all sections". Default "all".
<code>...</code>	Passed to <code>explode_sf()</code> or <code>explode_grouped()</code> .

Value

An `exploded_map` or `grouped_exploded_map` object with recombined focus/context geometry and extra diagnostics.

Examples

```
poly <- function(xmin, ymin, xmax, ymax) {
  sf::st_polygon(list(rbind(
    c(xmin, ymin), c(xmax, ymin), c(xmax, ymax),
    c(xmin, ymax), c(xmin, ymin)
  )))
}

municipalities <- sf::st_sf(
  NAME = c("A", "B", "C", "D"),
  nj_region = c("South", "South", "North", "North"),
  county_name = c("Atlantic", "Cape May", "Bergen", "Hudson"),
  geometry = sf::st_sfc(
    poly(0, 0, 1000, 1000),
    poly(2000, 0, 3000, 1000),
    poly(0, 2000, 1000, 3000),
    poly(2000, 2000, 3000, 3000),
    crs = 3857
  )
)

focused <- explode_section(
  municipalities,
  section_col = "nj_region",
  section = "South",
  region_col = "county_name",
  alpha_r = 1800,
```

```
alpha_l = 1200,  
plot = FALSE,  
quiet = TRUE  
)  
  
focus_map(  
  focused,  
  label_col = "NAME",  
  context_col = ".explodemap_role",  
  context_mode = "fade"  
)
```

explode_sf

Explode any sf object with an existing grouping column

Description

Explode any sf object with an existing grouping column

Usage

```
explode_sf(  
  sf_obj,  
  region_col = "region",  
  gamma_r = 3,  
  gamma_l = 1.136,  
  p = 1.25,  
  alpha_r = NULL,  
  alpha_l = NULL,  
  refine = FALSE,  
  refine_min_gap = NULL,  
  refine_max_shift = NULL,  
  refine_max_iter = 20,  
  refine_step = 0.5,  
  refine_within = c("region", "all"),  
  allow_other = FALSE,  
  fix_invalid = TRUE,  
  centroid_fun = c("centroid", "point_on_surface"),  
  plot = TRUE,  
  export = NULL,  
  label = "Custom Dataset",  
  quiet = FALSE  
)
```

Arguments

sf_obj Projected sf object (metric CRS)

region_col	Name of the column defining groups
gamma_r	Regional clearance coefficient (default 3.0)
gamma_l	Local clearance coefficient (default 1.136)
p	Distance scaling exponent (default 1.25)
alpha_r	Optional manual override for regional separation (metres). May be supplied independently of alpha_l.
alpha_l	Optional manual override for local expansion (metres). May be supplied independently of alpha_r.
refine	If TRUE, apply a bounded collision-refinement pass after the analytical displacement. Default is FALSE.
refine_min_gap	Optional minimum boundary-to-boundary gap in map units. If NULL and refine = TRUE, uses 2% of the characteristic diameter.
refine_max_shift	Optional maximum correction per feature in map units. If NULL and refine = TRUE, uses 10% of alpha_r + alpha_l.
refine_max_iter	Maximum refinement iterations.
refine_step	Fraction of each gap deficit corrected per iteration.
refine_within	Refine pairs within each "region" (default) or across "all" features.
allow_other	If TRUE, permits "Other" units
fix_invalid	If TRUE, auto-repairs invalid geometries
centroid_fun	"centroid" (default) or "point_on_surface"
plot	Print plots on return. Automatically suppressed when called inside a live Shiny session; use <code>plot.exploded_map()</code> inside <code>renderPlot()</code> instead.
export	NULL, TRUE, or file path
label	Title for plots
quiet	If TRUE, suppress all <code>message()</code> output. Default FALSE.

Value

An `exploded_map` S3 object

`explode_sf_with_lookup`

Explode any sf object using an external lookup table

Description

Joins the lookup to `sf_obj` before exploding. Unmatched units are labelled "Other".

Usage

```
explode_sf_with_lookup(
  sf_obj,
  join_col,
  lookup,
  lookup_key = join_col,
  region_col = "region",
  quiet = FALSE,
  ...
)
```

Arguments

sf_obj	Projected sf object
join_col	Column in sf_obj to join on
lookup	data.frame with join key and region column
lookup_key	Column name in lookup matching join_col
region_col	Column name in lookup containing region labels
quiet	If TRUE, suppress message() output. Default FALSE. Passed through to <code>explode_sf()</code> .
...	Passed to <code>explode_sf()</code>

Value

An exploded_map S3 object

explode_state	<i>Explode a US state from TIGER/Line data</i>
---------------	--

Description

Downloads municipal boundaries automatically, groups by county-to-region mapping, derives parameters via Analytical Results 1-2, and returns an exploded_map S3 object.

Usage

```
explode_state(
  state_fips,
  crs,
  region_map,
  gamma_r = 3,
  gamma_l = 1.136,
  p = 1.25,
  alpha_r = NULL,
  alpha_l = NULL,
  refine = FALSE,
```

```

refine_min_gap = NULL,
refine_max_shift = NULL,
refine_max_iter = 20,
refine_step = 0.5,
refine_within = c("region", "all"),
allow_other = FALSE,
fix_invalid = TRUE,
centroid_fun = c("centroid", "point_on_surface"),
plot = TRUE,
export = NULL,
label = paste0("FIPS ", state_fips),
quiet = FALSE
)

```

Arguments

state_fips	2-digit FIPS code (e.g. "34" for NJ)
crs	Projected CRS EPSG code (metric units)
region_map	Named list: region_name -> character vector of county names
gamma_r	Regional clearance coefficient (default 3.0)
gamma_l	Local clearance coefficient (default 1.136)
p	Distance scaling exponent (default 1.25)
alpha_r	Optional manual override for regional separation (metres). May be supplied independently of alpha_l.
alpha_l	Optional manual override for local expansion (metres). May be supplied independently of alpha_r.
refine	If TRUE, apply a bounded collision-refinement pass after the analytical displacement. Default is FALSE.
refine_min_gap	Optional minimum boundary-to-boundary gap in map units. If NULL and refine = TRUE, uses 2% of the characteristic diameter.
refine_max_shift	Optional maximum correction per feature in map units. If NULL and refine = TRUE, uses 10% of alpha_r + alpha_l.
refine_max_iter	Maximum refinement iterations.
refine_step	Fraction of each gap deficit corrected per iteration.
refine_within	Refine pairs within each "region" (default) or across "all" features.
allow_other	If TRUE, permits units mapped to "Other"
fix_invalid	If TRUE, auto-repairs invalid geometries
centroid_fun	"centroid" (default) or "point_on_surface"
plot	Print plots on return (default TRUE). Automatically suppressed when called inside a live Shiny session; use <code>plot.exploded_map()</code> inside <code>renderPlot()</code> instead.
export	NULL (no export), TRUE (auto-named GeoJSON), or a file path

label	Title for plots and print output
quiet	If TRUE, suppress all message() output (useful inside Shiny reactive() and observe() where messages are invisible to users). Default FALSE.

Value

An exploded_map S3 object

export_topojson	<i>Export an exploded map as TopoJSON</i>
-----------------	---

Description

Converts an sf, exploded_map, or grouped_exploded_map object to TopoJSON using the external mapshaper command-line tool. The input is first written as a temporary GeoJSON file, then converted by mapshaper.

Usage

```
export_topojson(x, file, simplify = NULL, overwrite = FALSE)
```

Arguments

x	An sf, exploded_map, or grouped_exploded_map object. For exploded_map objects, the WGS84 exploded geometry (sf_exp_wgs) is exported. For grouped_exploded_map objects, the WGS84 grouped geometry (sf_grouped_wgs) is exported.
file	Output file path. Should end in .topojson or .json.
simplify	Optional simplification proportion passed to mapshaper -simplify. Must be a single number between 0 and 1 (exclusive). For example, simplify = 0.5 retains 50% of vertices. Default is NULL (no simplification). Note that simplification modifies polygon geometry and therefore breaks the exact geometry preservation guarantee of Proposition 1.
overwrite	Logical; if TRUE, overwrite file if it already exists. Default is FALSE.

Details

This is intended as a convenience helper for downstream tools such as Power BI, D3.js, and Observable that prefer or require TopoJSON input.

This function requires the external mapshaper command-line tool to be installed and available on the system path. It can be installed with:

```
npm install -g mapshaper
```

The mapshaper tool is not an R package dependency; it is invoked via system2(). If mapshaper is not found, the function errors with an informative message.

Value

Invisibly returns the output file path.

Examples

```
## Not run:
# Two-level export
result <- explode_sf(my_sf, region_col = "region", plot = FALSE)
export_topojson(result, "exploded.topojson")

# Three-level grouped export
grp <- explode_grouped(my_sf, region_col = "region", plot = FALSE)
export_topojson(grp, "grouped.topojson")

# With simplification (breaks Proposition 1 guarantee)
export_topojson(result, "simplified.topojson", simplify = 0.5)

# Raw sf object
export_topojson(my_sf, "raw.topojson", overwrite = TRUE)

## End(Not run)
```

focus_map

Interactive focus-map viewer

Description

Renders spatial features as a smooth, interactive SVG map. Click any polygon to zoom in and lift it from the map with a "toast" effect; right-click or press Escape to reset. Camera transitions use D3's optimal zoom interpolation for fluid 60 fps motion with zero server round-trips.

Usage

```
focus_map(
  x,
  label_col = NULL,
  id_col = NULL,
  group_col = NULL,
  group_palette = NULL,
  context_col = NULL,
  context_values = "context",
  context_mode = c("fade", "hide", "show"),
  context_fill = "#cfd9df",
  context_opacity = 0.18,
  context_clickable = FALSE,
  focus_preset = c("none", "municipal", "drilldown", "municipal_drilldown"),
  simplify = TRUE,
```

```

    fill = "#2d6ea3",
    fill_opacity = 0.58,
    stroke = "#ffffff",
    lift_scale = 1.16,
    focus_padding = 40,
    focus_size = 0.76,
    min_focus_width = 0,
    min_focus_height = 0,
    tiny_feature_threshold = 48,
    tiny_feature_boost = 1,
    max_zoom = NULL,
    origin_context = c("none", "socket", "inset", "both"),
    origin_context_position = c("bottom-left", "bottom-right", "top-left", "top-right"),
    focus_context_opacity = 0.3,
    show_drag_zoom = FALSE,
    font_size = 14,
    show_labels = TRUE,
    show_sidebar = TRUE,
    performance_mode = NULL,
    info_cols = NULL,
    info_labels = NULL,
    info_title = NULL,
    info_position = c("top-right", "top-left", "bottom-right", "bottom-left"),
    info_card_scale = 1,
    area_min = 5000,
    width_min = 95,
    height_min = 28,
    width = "100%",
    height = "600px",
    elementId = NULL
  )

  focusmapOutput(outputId, width = "100%", height = "600px")

  renderFocusmap(expr, env = parent.frame(), quoted = FALSE)

```

Arguments

x	An sf, exploded_map, or grouped_exploded_map object.
label_col	Character. Column name for polygon labels. Auto-detected if NULL.
id_col	Optional stable feature ID column for Shiny selection events. Defaults to row order if NULL.
group_col	Character. Optional column for region/group colouring. Polygons sharing a group value share a hue.
group_palette	Optional named character vector of colours for group_col values. Names should match group values; unmatched groups fall back to the widget palette.
context_col	Optional column identifying features that should remain as geographic context rather than active focus features.

context_values	Character vector of values in context_col that mark context features. Default "context".
context_mode	How context features are drawn: "fade" keeps them visible but muted, "hide" makes them invisible, and "show" draws them normally.
context_fill	Fill colour for context features when context_mode = "fade".
context_opacity	Fill opacity for faded context features.
context_clickable	Should context features remain clickable? Default FALSE.
focus_preset	Optional named preset for common interactive workflows. "municipal" tunes small-area focus, source cues, drag zoom, and dense layer performance. "drilldown" tunes context fading and source cues for selected-section maps. "municipal_drilldown" combines both. Explicit arguments supplied by the user override preset defaults.
simplify	Controls geometry simplification for rendering performance. TRUE (default) applies a sensible tolerance (dTolerance = 0.001 in WGS 84 degrees, ≈ 100 m). A positive number sets a custom tolerance. FALSE disables simplification. Only affects the widget copy — the original data is never modified.
fill	Fill colour (used when group_col is NULL). Default "#2d6ea3".
fill_opacity	Fill opacity. Default 0.58.
stroke	Stroke colour. Default "#ffffff".
lift_scale	Initial toast lift scale. Default 1.16. Increase this to make the lifted feature larger.
focus_padding	Extra screen-space padding in pixels around the lifted feature during focus. Increase this if large lifted features feel too close to the map edge.
focus_size	Target fraction of the map viewport the lifted feature may occupy. Increase this to make selected areas appear larger while preserving focus_padding.
min_focus_width, min_focus_height	Minimum focused feature width and height in screen pixels. When a selected feature is very small, the widget may zoom past the usual density-aware default until the lifted feature reaches these dimensions. Set to 0 to disable either constraint.
tiny_feature_threshold	Screen-pixel size below which a selected feature receives an adaptive lift-scale boost. Set to 0 to disable.
tiny_feature_boost	Maximum multiplier applied to lift_scale for the smallest features. Values below 1 are not allowed.
max_zoom	Optional maximum camera zoom. If NULL, a density-aware default is used.
origin_context	How the selected feature's source location should be shown while focused. The default "none" keeps focus maps visually unchanged unless this feature is explicitly enabled. "socket" keeps the source outline in the main map, "inset" shows a small overview map, "both" uses both, and "none" disables the cue.
origin_context_position	Position for the overview inset: "bottom-left", "bottom-right", "top-left", or "top-right".

focus_context_opacity	Fill opacity for non-selected features while a feature is focused. Lower values make tiny selected areas easier to read.
show_drag_zoom	Show a widget-level drag-zoom toggle. When enabled, users can draw a marquee rectangle to zoom into dense clusters while ordinary feature clicks continue to focus the map. Shift-drag works as a shortcut even when the button is hidden.
font_size	Label font size in px. Default 14.
show_labels	Show labels on lifted shapes? Default TRUE.
show_sidebar	Deprecated and has no effect. Will be removed in a future version.
performance_mode	Logical or NULL. If NULL, dense layers automatically use shorter camera transitions and lighter in-flight rendering. Set TRUE to force it or FALSE to disable it.
info_cols	Optional character vector of columns to show in a non-blocking focus card when a feature is selected.
info_labels	Optional named character vector or list for display labels in the focus card. Names should match info_cols.
info_title	Optional column to use as the focus card title. Defaults to label_col.
info_position	Position for the focus card: "top-right", "top-left", "bottom-right", or "bottom-left".
info_card_scale	Relative size for the focus card. Values above 1 make the card larger; values below 1 make it more compact.
area_min	Min screen area (px ²) for label visibility.
width_min	Min screen width (px) for label visibility.
height_min	Min screen height (px) for label visibility.
width	Widget width. Default "100%".
height	Widget height. Default "600px".
elementId	Optional element ID.
outputId	Shiny output ID.
expr	Expression that returns a focus_map() widget.
env	Environment in which to evaluate expr.
quoted	Logical. Is expr already quoted?

Details

Accepts raw sf objects, exploded_map results from [explode_sf](#), or grouped_exploded_map results from [explode_grouped](#). For exploded objects, the displaced (WGS 84) geometry is used automatically.

Value

An htmlwidgets object.

Examples

```

poly <- function(xmin, ymin, xmax, ymax) {
  sf::st_polygon(list(rbind(
    c(xmin, ymin), c(xmax, ymin), c(xmax, ymax),
    c(xmin, ymax), c(xmin, ymin)
  )))
}

counties <- sf::st_sf(
  NAME = c("A", "B"),
  region = c("North", "South"),
  geometry = sf::st_sfc(
    poly(-74.2, 40.0, -74.0, 40.2),
    poly(-73.9, 40.0, -73.7, 40.2),
    crs = 4326
  )
)

focus_map(counties, label_col = "NAME", group_col = "region")

```

focus_map_preset

Focus-map option presets

Description

Returns a named list of `focus_map()` arguments for common interactive mapping workflows. Presets are intentionally plain lists so they can be inspected, modified, or passed through `do.call()`.

Usage

```

focus_map_preset(
  name = c("municipal", "drilldown", "municipal_drilldown", "none")
)

```

Arguments

name	Preset name. "municipal" tunes small-area focus maps with adaptive sizing, source cues, drag zoom, and dense-layer performance. "drilldown" tunes selected-section maps with faded context and source cues. "municipal_drilldown" combines both.
------	--

Value

A named list of `focus_map()` arguments.

Examples

```

focus_map_preset("municipal")

```

layout_regions	<i>Compute region anchor positions for grouped layouts</i>
----------------	--

Description

Implements the anchor layout procedure from Section 12. Supports three modes: automatic radial placement, automatic with collision resolution, and manual user-specified anchors.

Usage

```
layout_regions(
  sf_obj,
  region_col,
  mode = c("auto", "auto_collision", "manual"),
  anchors = NULL,
  kappa = 1.8,
  padding = 50000,
  delta = 15000,
  lambda = 0.18,
  eta = 0.18,
  padding_sep = 20000,
  max_iter = 60,
  quantile_p = 0.85,
  centroid_fun = c("centroid", "point_on_surface"),
  quiet = FALSE
)
```

Arguments

sf_obj	Projected sf object with region column
region_col	Grouping column name
mode	"auto" (radial only), "auto_collision" (radial + solver), or "manual"
anchors	For mode = "manual": data.frame with columns (region_col, anchor_x, anchor_y)
kappa	Radial expansion factor (default 1.8)
padding	Base padding in map units (default 50000)
delta	Log-density scaling factor (default 15000)
lambda	Spring coefficient for collision solver (default 0.18)
eta	Repulsion step size for collision solver (default 0.18)
padding_sep	Minimum separation between blocks (default 20000)
max_iter	Max iterations for collision solver (default 60)
quantile_p	Quantile for block radius estimation (default 0.85)
centroid_fun	"centroid" or "point_on_surface"
quiet	If TRUE, suppress message() output. Default FALSE.

Value

data.frame with region, anchor_x, anchor_y, block_radius, n_units

plot.exploded_map *Plot an exploded_map object*

Description

Plot an exploded_map object

Usage

```
## S3 method for class 'exploded_map'
plot(x, which = c("exploded", "original", "both"), ...)
```

Arguments

x	An exploded_map object
which	"exploded" (default), "original", or "both"
...	Ignored

Value

Invisibly returns x, the original exploded_map object. The method is called for its side effect of drawing the stored ggplot2 original and/or exploded map objects.

plot.grouped_exploded_map
 Plot a grouped_exploded_map object

Description

Plot a grouped_exploded_map object

Usage

```
## S3 method for class 'grouped_exploded_map'
plot(x, which = c("grouped", "original", "local", "all"), ...)
```

Arguments

x	A grouped_exploded_map object
which	"grouped" (default), "original", "local", or "all"
...	Ignored

Value

Invisibly returns `x`, the original `grouped_exploded_map` object. The method is called for its side effect of drawing the stored `ggplot2` grouped, original, and/or local map objects.

```
print.exploded_map    Print an exploded_map object
```

Description

Print an `exploded_map` object

Usage

```
## S3 method for class 'exploded_map'
print(x, ...)
```

Arguments

<code>x</code>	An <code>exploded_map</code> object
<code>...</code>	Ignored

Value

Invisibly returns `x`, the original `exploded_map` object. The method is called for its side effect of printing a compact diagnostic overview of units, regions, derived parameters, and optional refinement information.

```
print.grouped_exploded_map
      Print a grouped_exploded_map object
```

Description

Print a `grouped_exploded_map` object

Usage

```
## S3 method for class 'grouped_exploded_map'
print(x, ...)
```

Arguments

<code>x</code>	A <code>grouped_exploded_map</code> object
<code>...</code>	Ignored

Value

Invisibly returns `x`, the original `grouped_exploded_map` object. The method is called for its side effect of printing a compact diagnostic overview of units, regions, grouping mode, and grouped-layout parameters.

`summary.exploded_map` *Summary of an exploded_map object*

Description

Summary of an `exploded_map` object

Usage

```
## S3 method for class 'exploded_map'
summary(object, ...)
```

Arguments

<code>object</code>	An <code>exploded_map</code> object
<code>...</code>	Ignored

Value

Invisibly returns `object`, the original `exploded_map` object. The method is called for its side effect of printing a human-readable summary of dataset size, geometry statistics, displacement parameters, refinement diagnostics, and implied calibration coefficients.

`summary.grouped_exploded_map`
 Summary of a grouped_exploded_map object

Description

Summary of a `grouped_exploded_map` object

Usage

```
## S3 method for class 'grouped_exploded_map'
summary(object, ...)
```

Arguments

<code>object</code>	A <code>grouped_exploded_map</code> object
<code>...</code>	Ignored

Value

Invisibly returns object, the original `grouped_exploded_map` object. The method is called for its side effect of printing dataset size, grouping diagnostics, anchor parameters, and anchor radii.

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